

# Discriminative Learning of Deep Convolutional Feature Point Descriptors

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## Objective

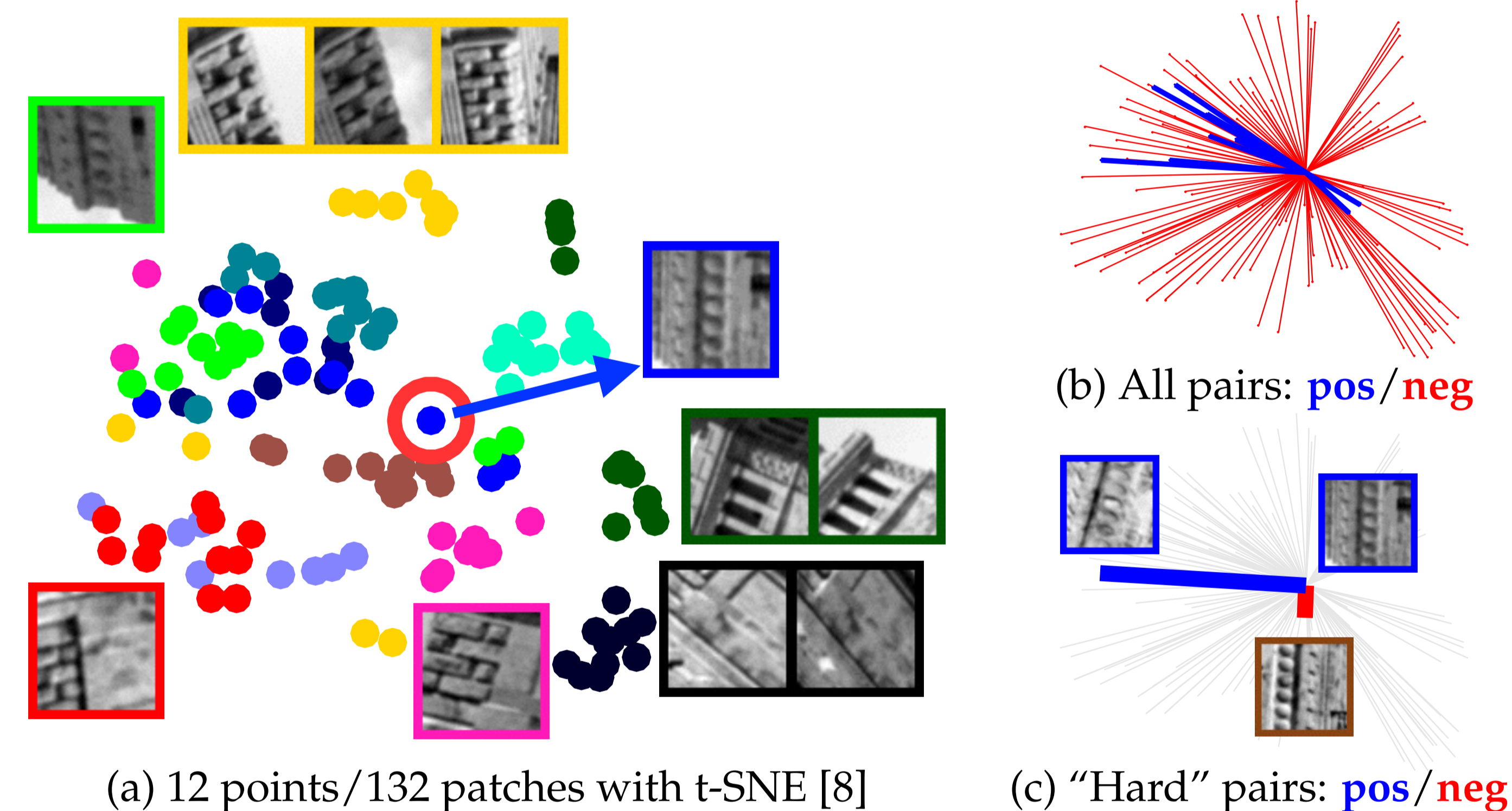
- Learn compact, discriminative representations of image patches with Convolutional Neural Networks.
- Optimize for comparisons with the  $L_2$  distance, i.e. no metric learning. Our descriptors work within existing pipelines.

## Main features

- Drop-in replacement for SIFT:** 128f, compare with the  $L_2$  norm.
- Consistent improvements** over the state of the art.
- Trained in one dataset, but **generalizes very well** to scaling, rotation, deformation and illumination changes.
- Computational efficiency (on GPU: 0.76 ms; dense SIFT: 0.14 ms). Code is available: <https://github.com/etrulls/deepdesc-release>

## Key observation

- We train a Siamese architecture with **pairs of patches**. We want to **bring matching pairs together and otherwise pull them apart**.
- Problem? Randomly sampled pairs are already **easy to separate**.
- Solution: To train discriminative networks we use **hard negative and positive mining**. This proves essential for performance.



We take samples from [1], for illustration. Corresponding patches are shown with same color: (a) Representation from t-SNE [8]. **Distance encodes similarity.**

(b) Random sampling: **similar (close) positives** and **different (distant) negatives**.

(c) We mine the samples to obtain dissimilar positives (+, **long blue segments**) and similar negatives (x, **short red segments**):

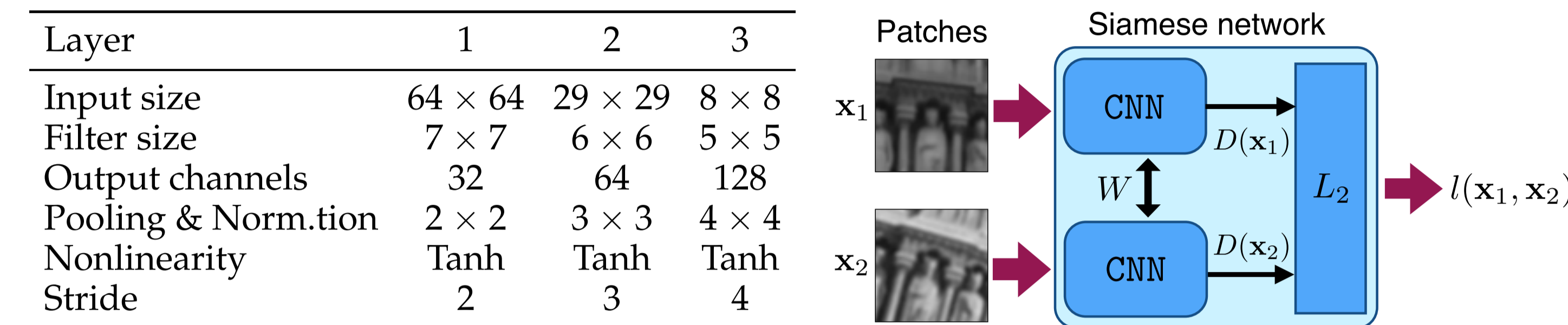
(d) Random sampling results in easy pairs.

(e) Mined pairs with harder correspondences.

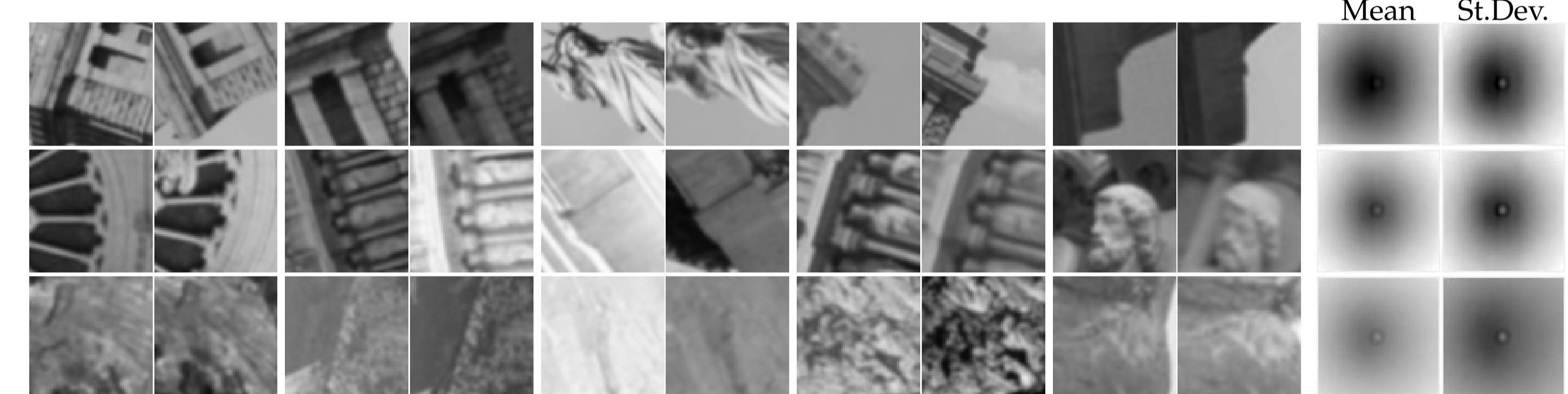
This allows us to train discriminative models with a small number of parameters (~45k), which also alleviates overfitting concerns.

## Model & Training

Our model is a **3-Layer Convolutional Neural Network**. For training we use a **siamese architecture** with weight sharing and SGD.



Train on the **MVS Dataset** [1]. 64 × 64 grayscale patches from SFM: Statue of Liberty (LY, top), NotreDame (ND, center), Yosemite (YO, bottom). ~150k points and ~450k patches each ⇒ **10<sup>6</sup> positive pairs** and **10<sup>12</sup> negative pairs** ⇒ Efficient exploration with mining.



We minimize the hinge embedding loss. With 3D point indices  $p_1, p_2$ :

$$l(\mathbf{x}_1, \mathbf{x}_2) = \begin{cases} \|D(\mathbf{x}_1) - D(\mathbf{x}_2)\|_2, & p_1 = p_2 \\ \max(0, C - \|D(\mathbf{x}_1) - D(\mathbf{x}_2)\|_2), & p_1 \neq p_2 \end{cases}$$

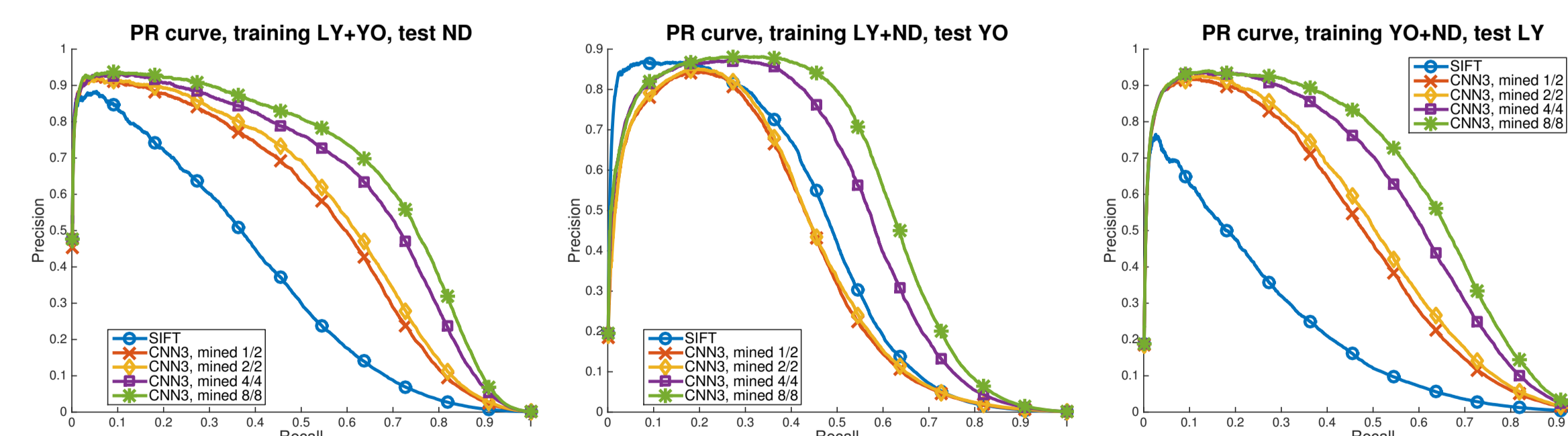
This penalizes corresponding pairs that are placed far apart, and non-corresponding pairs that are less than  $C$  units apart.

**Methodology:** Train over two sets and test over third (*leave-one-out*), with cross-validation. Metric: **precision-recall** (PR). 'Needle in a haystack' setting: pick **10k unique points** and generate **one positive pair** and **1k negative pairs** for each, i.e. 10k positives vs. 10M negatives. Results summarized by 'Area Under the Curve' (AUC).

## Effect of mining

(a) Forward-propagate positives  $s_p \geq 128$  and negatives  $s_n \geq 128$ .

(b) Pick the 128 with the largest loss (for each) and back-propagate.



$s_p$	$s_n$	PR AUC
128	128	0.366
256	256	0.374
512	512	0.369
1024	1024	0.325

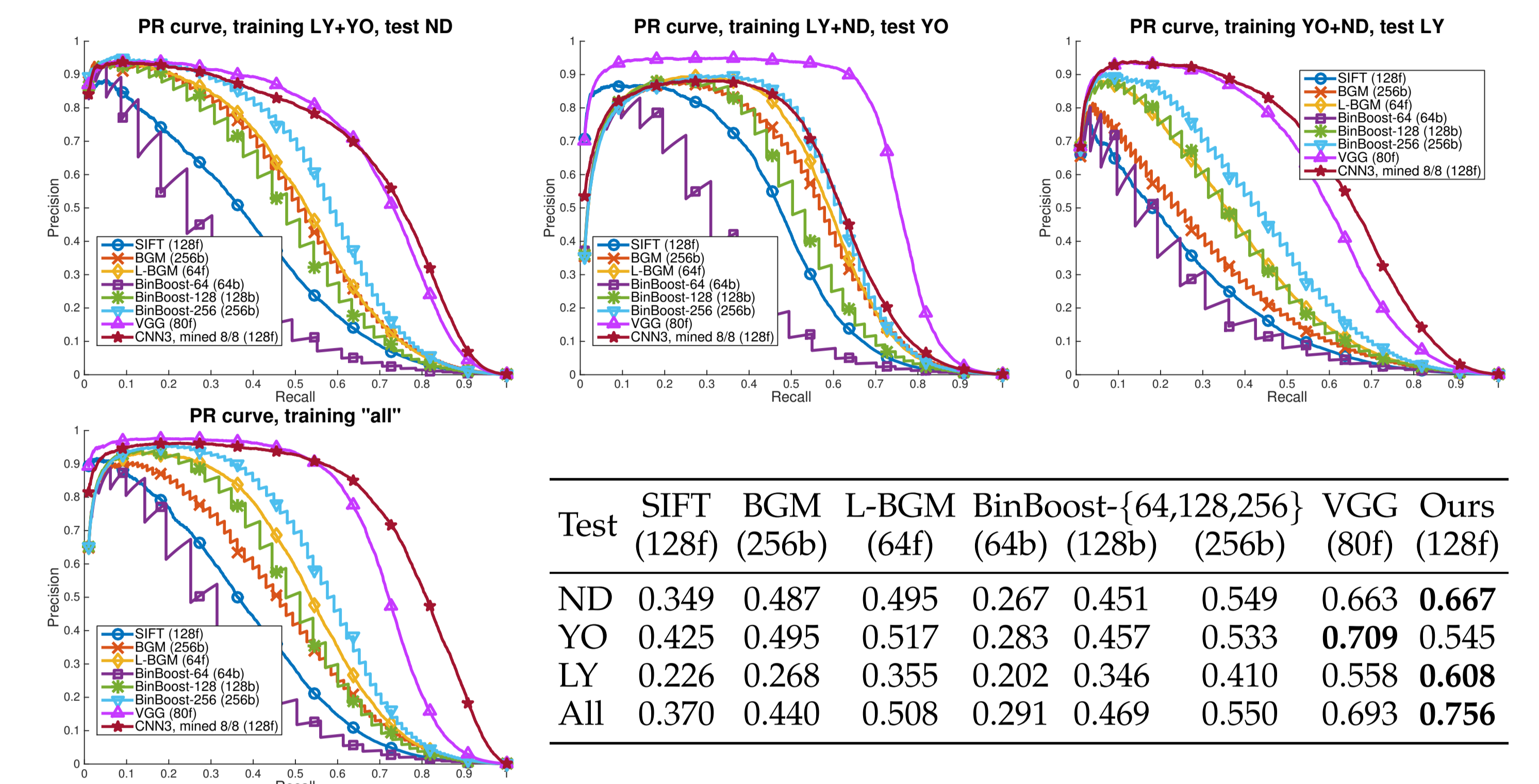
**Table 1:** (a) No mining. Larger batches **do not help**.

$s_p$	$s_n$	$r_p$	$r_n$	Cost	PR AUC
128	256	1	2	20%	0.558
256	256	2	2	35%	0.596
512	512	4	4	48%	0.703
1024	1024	8	8	67%	0.746

**Table 2:** (b) Mining with  $r_p = s_p/128, r_n = s_n/128$ . The mining cost is incurred **during training only**.

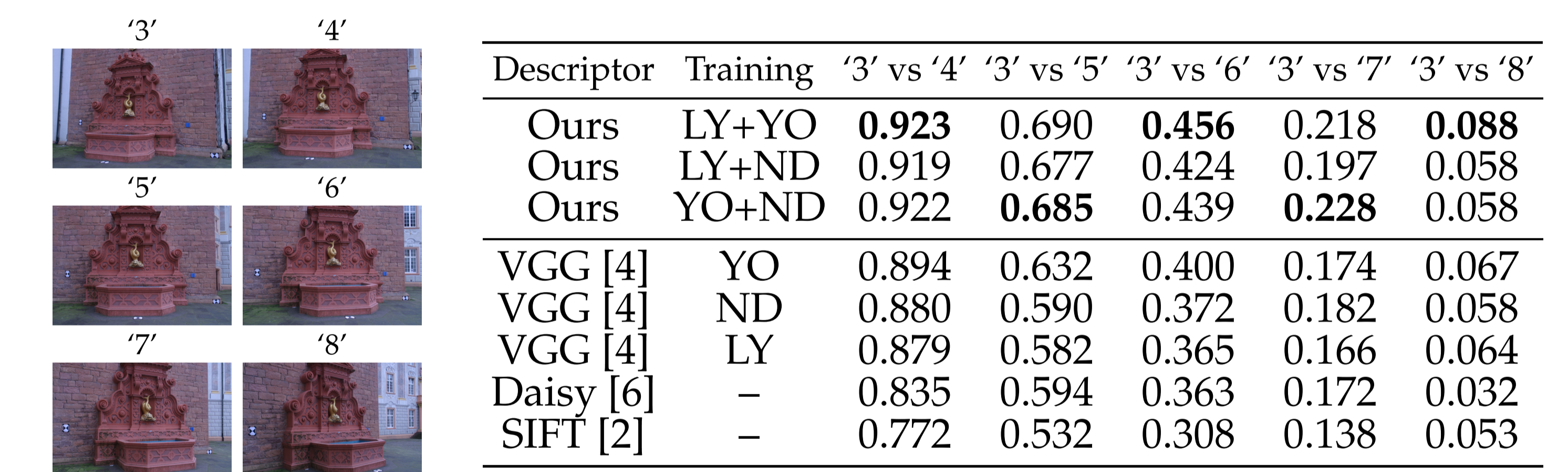
## Comparison with the state-of-the-art on MVS

We benchmark our models against SIFT, BinBoost [7], and VGG [4]. Better performance on 2/3 splits. Why? YO is very different from LY/ND (e.g. mean/std). Training on all three sets: top performance.



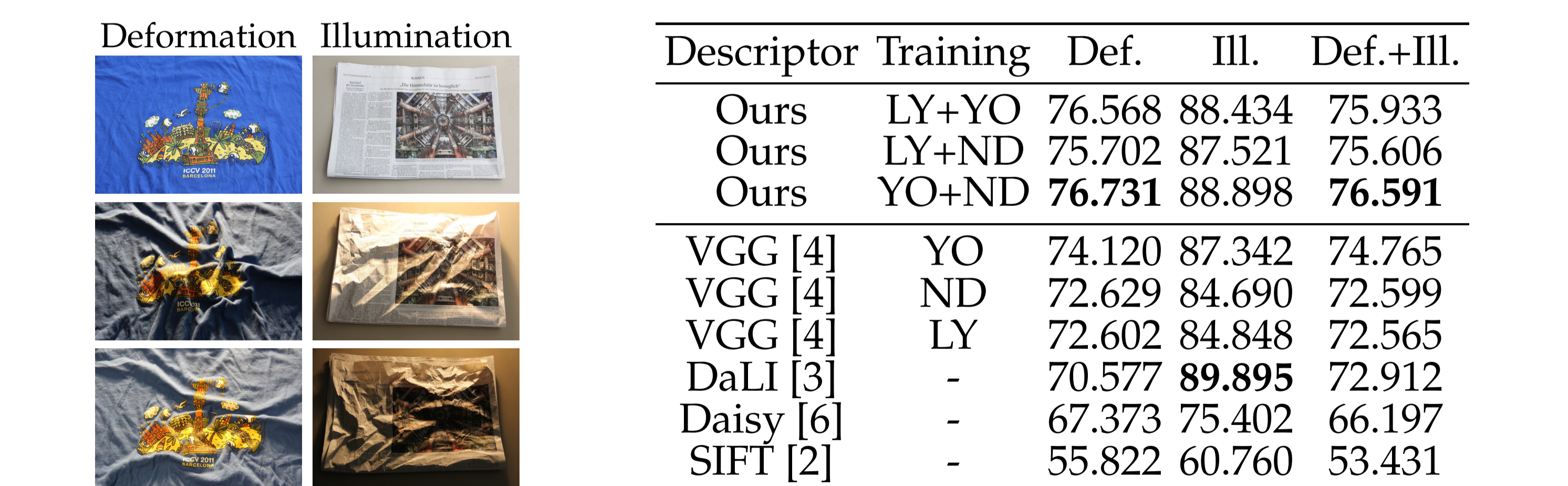
## Generalization: Wide-Baseline Matching

Data from [5]. We match a set of points from view '3' against '4' to '8' (increasing baseline) and build PR curves, as before. No re-training.



## Generalization: Deformation and Illumination

Our models outperform the state-of-the-art on illumination changes and non-rigid deformations [3] without re-training or fine-tuning.



## References

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